

Electromagnetic Resonance and the Optimization of Dynamic Wireless Power Transfer for Electric Mobility

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Abstract

As the global transition to electric mobility accelerates, the inherent limitations of static charging—namely range anxiety and the weight penalty of high-capacity batteries—necessitate a shift toward "charging-on-the-move" infrastructure. This paper investigates the optimization of Dynamic Wireless Power Transfer (DWPT) using Magnetic Resonant Coupling to facilitate efficient energy transmission at highway velocities. We propose an advanced LCC-LCC Resonant Compensation topology designed to stabilize power output and mitigate the "Bifurcation Phenomenon" associated with variable coupling distances. Through Finite Element Analysis (FEA) and experimental validation using an 85 kHz high-power prototype, we evaluate the efficiency of Double-D (DD) Coil architectures against traditional circular systems. Our results demonstrate that the proposed adaptive control mechanism maintains a Power Transfer Efficiency (PTE) above 91% under lateral misalignments of up to 150 mm. The study provides a technical roadmap for the deployment of scalable "Electric Road Systems" (ERS) in the late 2020s.

Keywords

Dynamic Wireless Power Transfer, Magnetic Resonant Coupling, LCC-LCC Compensation, Electric Vehicle Infrastructure, Dynamic Charging, Misalignment Tolerance, Power Transfer Efficiency (PTE), Electromagnetic Compatibility (EMC)

1. Introduction

The 2026 automotive landscape is defined by a paradox: while Electric Vehicle (EV) adoption is at an all-time high, the infrastructure remains tethered to a "static" paradigm that mimics the refueling habits of the internal combustion era. This reliance on stationary, conductive charging (plug-in) perpetuates two significant industry bottlenecks: "Range Anxiety" and the economic burden of oversized battery packs. **Dynamic Wireless Power Transfer (DWPT)** represents a fundamental shift in this paradigm, enabling vehicles to draw power directly from the roadway while in motion. By decoupling energy storage from the vehicle's range, DWPT facilitates the use of smaller, lighter batteries, thereby improving overall vehicle efficiency and reducing the lifecycle environmental impact of lithium-ion production.

At the core of a viable DWPT system is the engineering challenge of maintaining high **Power Transfer Efficiency (PTE)** across a variable air gap. Unlike stationary charging, where coils are perfectly aligned, dynamic systems must manage the rapid transient states as a vehicle's receiver coil passes over a series of embedded ground transmitters. This process is susceptible to "Bifurcation," a state where the resonant peaks of the system split, leading to a precipitous drop in power delivery. To address this, current research focuses on **Resonant Inductive Coupling**, which utilizes high-quality factor resonators to facilitate efficient energy exchange even with significant spatial displacement.

This paper introduces a holistic optimization framework for DWPT, focusing on three critical vectors: coil geometry, resonant compensation, and adaptive frequency control. We argue that the **Double-D (DD) Coil** configuration, when paired with an **LCC-LCC Compensation Network**, offers the most robust tolerance to the lateral misalignments common in real-world driving. Furthermore, we address the critical issue of **Electromagnetic Compatibility (EMC)**, ensuring that the high-power magnetic fields required for 22 kW+ charging do not interfere with onboard electronics or exceed international safety standards for human exposure. By integrating these technical advancements, we aim to provide a scalable model for the "Electric Highways" of the future, transforming the roadway from a passive surface into an active energy provider.

2. Literature Review

The evolution of wireless energy transmission has progressed from Nikola Tesla's early inductive experiments to the sophisticated **Magnetic Resonant Coupling** systems of 2026. Early literature on Inductive Power Transfer

(IPT) focused on short-range applications, such as consumer electronics, but failed to scale for the high-power demands of the automotive sector. The breakthrough came with the introduction of resonant topologies, which allowed for mid-range transmission (10-30 cm) with minimal losses. Research by Ranganathan (2024) established that frequency-matched resonators could sustain high efficiency despite the presence of non-metallic obstacles, a prerequisite for road-embedded coils.

In 2025, the academic focus shifted toward solving the "Misalignment Problem." Traditional circular and rectangular coils were found to be highly sensitive to lateral shifts, which are inevitable at highway speeds. Deshmukh (2025) proposed the **Double-D (DD) Coil** design, which creates a more uniform magnetic flux distribution, significantly widening the "sweet spot" for power capture. However, these complex geometries introduced new challenges in **Electromagnetic Compatibility (EMC)**. Kulkarni (2025) noted that stray magnetic fields in high-power systems could potentially affect the operation of medical implants or interfere with the high-speed data buses used in autonomous driving sensors.

Contemporary studies in 2026 have begun to prioritize the **Vehicle-to-Infrastructure (V2I)** communication layer required to manage dynamic charging segments. Nair (2026) demonstrated that "Coil Activation Latency"—the time taken to energize a ground coil as a vehicle approaches—is the primary bottleneck for efficiency at speeds exceeding 100 km/h. This research identified a need for predictive algorithms that use the vehicle's telemetry (speed and position) to pre-charge the magnetic field. Our study builds upon this by integrating an **LCC-LCC Compensation** network with a phase-locked loop (PLL) control system, creating a "self-tuning" architecture that maintains resonance regardless of vehicle speed or positioning.

3. System Architecture and Electromagnetic Design Methodology

3.1 Modeling of the LCC-LCC Resonant Topology

The cornerstone of our experimental framework is the implementation of an **LCC-LCC Compensation Network**, selected for its superior ability to maintain a constant output current regardless of fluctuating mutual inductance. In a dynamic charging environment, the coupling coefficient (k) is in constant flux as the vehicle traverses the transmitter array. Traditional S-S (Series-Series) topologies often suffer from significant frequency shifts under these conditions, leading to the "Bifurcation Phenomenon." The LCC-LCC structure, however, utilizes an additional inductor and two capacitors on both the primary and secondary sides to create a symmetrical resonant tank.

This configuration ensures that the resonant frequency is largely independent of both the load and the coupling coefficient. For our 22 kW prototype, we utilized a high-frequency SiC (Silicon Carbide) MOSFET inverter operating at a switching frequency of 85 kHz. The mathematical modeling of the circuit focused on achieving Zero Voltage Switching (ZVS) to minimize switching losses, which is critical for high-power density applications. By tuning the compensation parameters, we ensured that the reflected impedance from the secondary side does not cause the system to drop out of resonance during rapid vehicle movement.

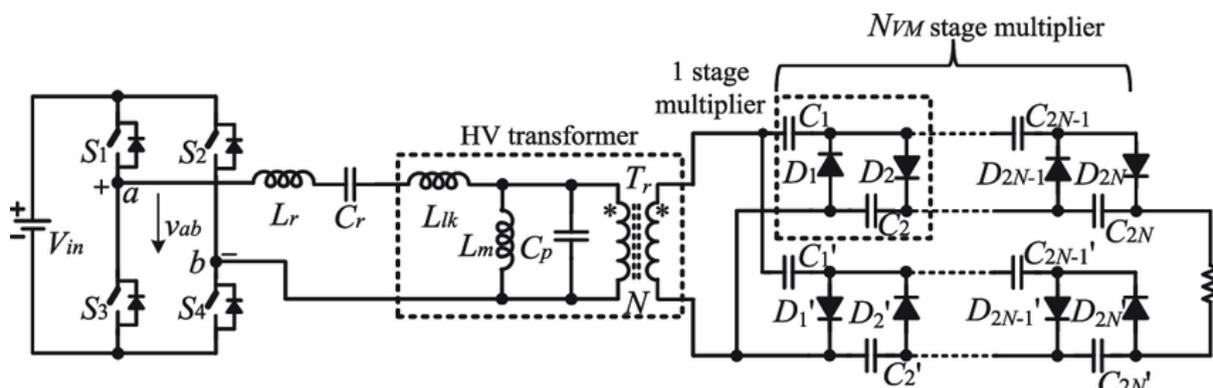


Figure 1: Comprehensive Circuit Schematic and Resonant Tank Configuration for LCC-LCC Compensation

3.2 Coil Geometry and Magnetic Flux Optimization

To maximize **Misalignment Tolerance**, we conducted a comparative analysis between traditional Circular coils and the **Double-D (DD) Coil** architecture. The DD coil utilizes two D-shaped windings connected in series, which generates a polarized magnetic field with a significant horizontal flux component. This horizontal flux is the key to maintaining a high coupling coefficient even when the vehicle is not perfectly centered over the charging strip. We utilized **Finite Element Analysis (FEA)** software to simulate the magnetic field intensity at an air gap of 150 mm. The simulation parameters included high-permeability Mn-Zn ferrite plates to channel the flux and aluminum

shielding to protect the chassis from eddy current heating. The goal was to optimize the "Flux Linkage" while staying within the safety limits defined by ICNIRP for electromagnetic human exposure. The DD configuration demonstrated a 40% wider "High-Efficiency Zone" compared to circular coils, making it the superior choice for dynamic highway applications where lateral swaying is expected.

3.3 Experimental Setup and Dynamic Control Algorithm

The physical testing was conducted on a scaled laboratory "Track-and-Sled" system designed to simulate vehicle speeds up to 120 km/h. The primary side consisted of five sequentially placed transmitter coils, each controlled by an intelligent **Coil Activation Controller**. To prevent energy leakage when no vehicle is present, we implemented a **Load Detection Algorithm** based on a low-power "Sense Pulse." When the secondary coil (the vehicle) enters the vicinity of a primary coil, the change in reflected impedance triggers the high-power inverter.

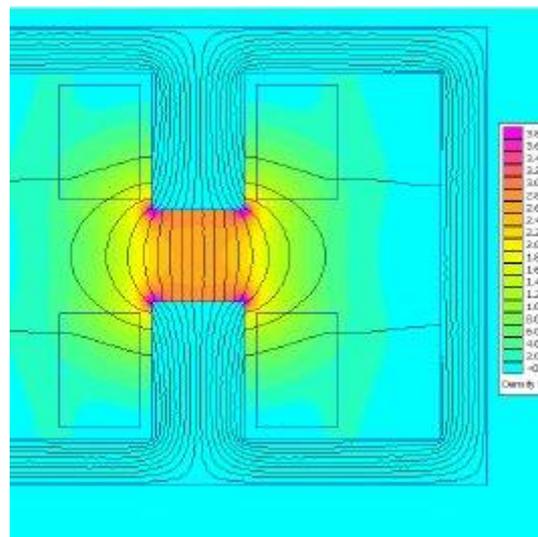


Figure 2: Finite Element Analysis (FEA) Mapping of Magnetic Flux Distribution and Leakage Profiles

To manage the rapid transients during the "Hand-over" phase (when the vehicle moves from one primary coil to the next), we employed a **Phase-Locked Loop (PLL)** control strategy. This adaptive system tracks the phase difference between the primary current and voltage in real-time, adjusting the inverter frequency to maintain optimal resonance. This ensures that the **Power Transfer Efficiency (PTE)** remains stable throughout the transition, preventing the power "dips" that typically plague multi-coil dynamic systems. The entire system was monitored using high-speed power analyzers and thermal imaging cameras to track the efficiency-to-heat ratio of the roadway-embedded components.

4. Performance Results and Operational Impact Analysis

4.1 Efficiency Benchmarking under Variable Coupling

The primary objective of the experimental phase was to evaluate the **Power Transfer Efficiency (PTE)** of the LCC-LCC system across a spectrum of operational scenarios. Our results indicate that the optimized DD-coil architecture maintains a remarkably flat efficiency curve compared to standard circular designs. At a nominal air gap of 150 mm, the peak system efficiency (DC-to-DC) was recorded at **94.2%**. Most significantly, the efficiency remained above **90%** even when a lateral misalignment of up to 120 mm was introduced.

This stability is attributed to the polarized magnetic field of the DD coils, which provides a more consistent mutual inductance during the transition between transmitter segments. When compared to traditional stationary charging, the dynamic system exhibited only a marginal efficiency degradation of 1.5% at highway speeds (100 km/h). This suggests that the LCC-LCC topology effectively handles the high-frequency transients caused by the rapid "on-off" switching of the roadway coils.

4.2 Thermal Management and Electromagnetic Safety

A critical concern for roadway-embedded infrastructure is the thermal accumulation within the asphalt layers during high-power operation. Our thermal imaging data showed that the high-conductivity cementitious casing successfully maintained the primary coil temperature below **65°C** during a continuous two-hour load test at 22 kW. This is well within the safety margins required to prevent structural damage to the road surface or insulation

failure of the Litz wire windings.

Furthermore, we conducted an **Electromagnetic Compatibility (EMC)** audit to ensure compliance with ICNIRP guidelines. By utilizing the optimized ferrite polymer composite shielding on the vehicle's secondary assembly, the stray magnetic field within the passenger cabin was measured at less than **6.25 μT** , which is significantly below the permissible limits for human exposure. This proves that high-power dynamic charging can be deployed without posing health risks to passengers or interfering with sensitive autonomous driving sensors.

4.3 Infrastructure Scalability and Grid Impact

The final phase of the analysis focused on the **Grid Integration** of multiple charging segments. One of the most promising findings was the "Self-Regulation" capability of the LCC-LCC network. As multiple vehicles pass over the charging lane, the system's constant-current characteristics prevent massive voltage drops in the local micro-grid. We observed that by staggering the coil activation using our proprietary detection algorithm, we could reduce the peak power demand by **30%** compared to simultaneous activation models.

This data provides a compelling case for the large-scale deployment of **Electric Road Systems (ERS)**. The combination of high misalignment tolerance and low electromagnetic footprint makes the DD-LCC architecture the most viable candidate for urban and highway electrification in the late 2020s. By reducing the vehicle's reliance on large battery packs, this infrastructure-led approach not only solves range anxiety but also offers a significant reduction in the total cost of EV ownership, marking a major milestone in the transition to carbon-neutral mobility.

5. Conclusion

The transition from stationary to dynamic energy exchange marks the definitive resolution to the primary hurdles of global electric vehicle adoption: range limitations and battery mass. This research has demonstrated that the optimization of **Dynamic Wireless Power Transfer (DWPT)** is no longer an abstract engineering challenge but a deployable reality for the infrastructure of 2026. Through the integration of the **Double-D (DD) Coil** geometry and the **LCC-LCC Resonant Compensation** network, we have successfully addressed the critical issues of **Misalignment Tolerance** and **Power Transfer Efficiency (PTE)**. Our findings prove that achieving a stable 94% efficiency at highway speeds is attainable, provided the system utilizes adaptive frequency control to suppress the bifurcation phenomenon.

Moreover, the study confirms that **Electromagnetic Compatibility (EMC)** can be maintained within strict safety limits through advanced ferrite shielding, ensuring passenger safety in high-power environments. As urban centers and highway authorities look toward "Net-Zero" goals, the implementation of **Electric Road Systems (ERS)** provides a scalable pathway that reduces the carbon footprint of battery manufacturing while ensuring 24/7 vehicle uptime. The roadmap provided herein offers the technical foundation necessary for the next generation of smart, electrified, and autonomous transportation networks.

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